

Multiagent Dynamics of Gradual Argumentation Semantics

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Motivation

- **Abstract argumentation** is a way of representing abstract arguments as networks
- Several functions have been developed to compute the strength of such arguments → **Gradual Semantics**

If agents indeed reason and interact using some gradual semantics, together with some protocol, how will debates and agents opinion evolve?

⇒ Normative point of view, but inspired by online debates.

Amgoud, L., Ben-Naim, J., Doder, D., & Vesic, S. *Acceptability semantics for weighted argumentation framework*. IJCAI 2017.

Agent polarization through exchange of arguments

Banisch, S., Olbrich, E. *An Argument Communication Model of Polarization and Ideological Alignment.* . JASSS 2021.

Abstract Argumentation in Opinion Diffusion

Butler, G., Pigozzi, G., Rouchier, J. *An opinion diffusion model with deliberation..* 20th International Workshop on Multi-Agent-Based Simulation 2019.

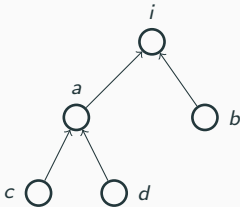
Taillandier, P., Salliou, N., Thomopoulos, R. *Introducing the Argumentation Framework Within Agent-Based Models to Better Simulate Agents' Cognition in Opinion Dynamics: Application to Vegetarian Diet Diffusion..* JASSS 2021.

1. Abstract argumentation theory
2. The protocol
3. Simulation Results
4. Conclusion

Abstract argumentation theory

Abstract Argumentation Theory

- Arguments are abstract: no content is analyzed
- $AF = \langle \mathcal{A}, \mathcal{R} \rangle$, where
 - \mathcal{A} is a finite and non-empty set of arguments
 - $\mathcal{R} \subseteq \mathcal{A} \times \mathcal{A}$ is an attack relation

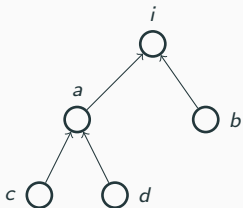


Dung, P. M.. *On the acceptability of arguments and its fundamental role in non-monotonic reasoning, logic programming and n-person games*. Artificial intelligence 1995.

Gradual Semantics

- Formal methods to assess the acceptability of arguments
- Gradual semantics: quantitative way to assess arguments
- A **gradual semantics** associates a scoring to each argument
 $S : \mathcal{A} \rightarrow \mathbb{R}$

For example, with the h-categorizer semantics:



- $Hbs(b) = Hbs(c) = Hbs(d) = 1$
- $Hbs(a) = 0.333$
- $Hbs(i) = 0.4286$

Amgoud, L., Ben-Naim, J., Doder, D., & Vesic, S. *Acceptability semantics for weighted argumentation framework*. IJCAI 2017.

The protocol

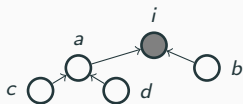
Profile of a Game

Issue Oriented Argumentation Graph (IOAG)

Each argument is part of a path towards the **issue** of the graph. The issue is the main question of the debate.

The **value** of the graph is the value of the issue.

The **Universe graph** contains every relevant argument of the debate:

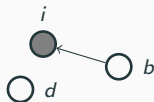


Universe graph, $V_{UG} = 0.4286$

Agents are each equipped with an **agent's graph**, subset of the universe graph



Agent 1, $V_1 = 0.75$

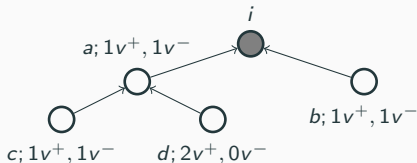


Agent 2, $V_2 = 0.5$

Merged graph

Merged graph

The **merged graph** is a weighted argumentation framework constructed from agent' graphs, where each agent holding an argument in her AF "virtually" vote for it, while the others vote against

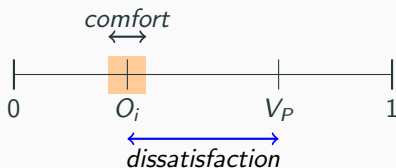


Merged graph, $V_{MG} = 0.6277$

→ this graph is a tool for analysing the debate

Evaluation and Strategies

Agent's goal: They want the public debate to reflect their opinion.



- **If not comfortable** : agents can play any argument which brings the V_P closer to their opinion.
- **If comfortable** : agents can play any argument which leaves the V_P in their comfort interval.

Dissatisfaction

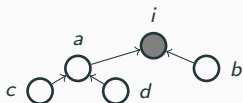
The **dissatisfaction** of an agent is the distance between the agent's opinion and the value of the public graph.

Learning Arguments

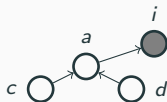
- After every step, agents can "learn" arguments : add the new arguments to their opinion graphs.
 - Learning is based on **confirmation bias** : agents are more likely to learn arguments which favor their opinion.
- Agent's opinion changes throughout the game.

An example course of the protocol

Universe Graph



Agent 1



$$O_1 = 0.75$$

Agent 2

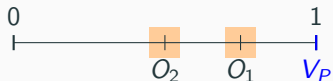


$$O_2 = 0.5$$

Public Graph

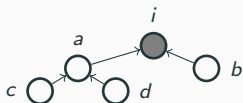


$$V_P = 1$$



An example course of the protocol

Universe Graph

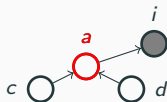


Public Graph



$$V_P = 1$$

Agent 1

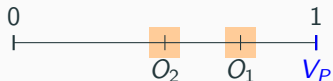


$$O_1 = 0.75$$

Agent 2

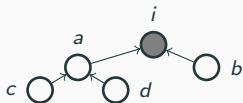


$$O_2 = 0.5$$

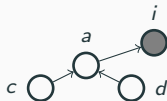


An example course of the protocol

Universe Graph

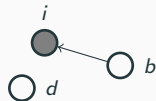


Agent 1



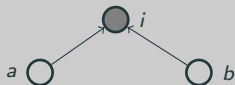
$$O_1 = 0.75$$

Agent 2

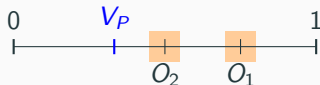


$$O_2 = 0.5$$

Public Graph

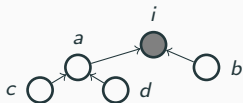


$$V_P = 0.33$$

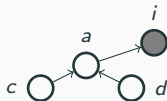


An example course of the protocol

Universe Graph

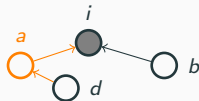


Agent 1



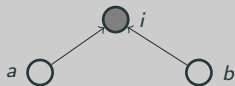
$$O_1 = 0.75$$

Agent 2

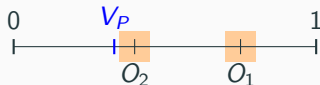


$$O_2 = 0.4$$

Public Graph

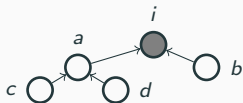


$$V_P = 0.33$$

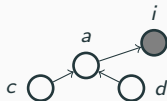


An example course of the protocol

Universe Graph

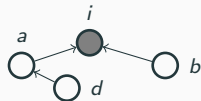


Agent 1



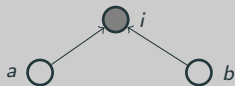
$$O_1 = 0.75$$

Agent 2

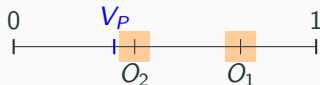


$$O_2 = 0.4$$

Public Graph



$$V_P = 0.33$$



Simulation Results

Hypotheses

- H1 : “Outcome”** For a given debate, if the learning probabilities increase, the outcome gets closer to the merged value.
- H2 : “Flexibility”** Increasing the size of the comfort zone increases the agent's satisfaction.
- H3 : “Open Mind”** If the learning probability of an agent increases, she will be more satisfied at the end of the debate.
- H4 : “Strength of the Group”** When many agents share the same initial information, they have a greater chance to be satisfied by the final result.
- H5 : “Power of Knowledge”** Agents that know more arguments at the beginning of the game are more satisfied at the end.
- H6 : “Convergence of Views”** The highest the learning probabilities, the lower the distance between the agent's final values.

	Variable 1	Variable 2	R	p value
H1	P_L	$ V_F - V_M $	-0,55029	2,44E-80
H2	c_l	N_C	0,680451	4,1E-137
H3	P_L	AD	-0,70346	2,1E-150
H4	Nb of Clones	AD_{clones}	-0,28678	2,19E-20
H5	$ Arg(DG_k) $	d_k	-0,40972	9,3E-38
H6	P_L	STD	-0,6683870	1,2764E-130

Table 1: Testing the hypotheses. Correlation level: Dark green = high, light green = moderate, yellow = low.

An improved protocol with votes

	Variable 1	Variable 2	R	p value
H1	P_L	$ V_F - V_M $	-0,0645	0,04
H2	c_l	N_C	0,604745	6,6E-101
H3	P_L	AD	-0,53363	1,39E-171
H4	Nb of Clones	AD_{clones}	-0,23606	3,94E-14
H5	$ Arg(DG_k) $	d_k	-0,40972	9,3E-38
H6	P_L	STD	-0.62242	1.8E-108

Table 2: Testing the hypotheses. Correlation level: Dark green = high, light green = moderate, yellow = low, red = no.

Conclusion

- We showed that a number of desirable hypotheses were verified.
- Our work shows that dynamics game of argumentation can be used to model the convergence of the opinion of agents.
- On the downside, one hypothesis was not verified any longer when we augment the protocol with votes, which reminds us of the importance of such seemingly minor design choices.